

ME 115(a): Homework #1

(Due Friday January 24, 2014)

Problem 1: (10 points) In class we considered that every planar rigid body displacement is *equivalent* to a rotation about a unique point in the plane, known as the pole.

Let A be a fixed reference frame. A rigid body, L, which has local frame B attached to it, is located relative to reference frame A by $D_1 = (\vec{d}_{01}, R_{01})$. Body L moves to position C, where the displacement to location C, as measured by an observer in frame B, is given by $D_2 = (\vec{d}_{12}, R_{12})$. Where is the *pole* of the body displacement from position B to position C, as a function of R_{01} , R_{12} , \vec{d}_{01} , and \vec{d}_{12} ?

- a. As measured in Frame A
- b. As measured in Frame B
- c. As measured in Frame C

Problem 2: (5 points) In the above problem, suppose $D_1 = (x, y, \theta) = (1.0, 2.0, 30.0^\circ)$ and $D_2 = (x, y, \theta) = (2.0, 3.0, 60^\circ)$. Where is the pole of the displacement from B to C in this case?

Problem 3: (15 points) Using the set up of Problem 1, pick a coordinate system whose origin is located at the pole of the displacement, and show that in this coordinate system, the displacement of the body from B to C is a pure rotation.

Problem 4: (10 points) (This is Problem 3(c) in Chapt. 2 of the MLS text). Let $R = [\vec{r}_1 \ \vec{r}_2 \ \vec{r}_3]$ be a rotation matrix (i.e., the \vec{r}_i are the columns of the matrix). Show that $\det(R) = \vec{r}_1^T(\vec{r}_2 \times \vec{r}_3)$

Problem 5: (15 points) Consider again the *Elliptical Trammel* that was analyzed in class, and whose diagram is repeated in Figure 1. As in the handout on the Elliptical Trammel, let **A** and **B** denote the points on the moving rigid body that coincide with the revolute joint axes, and let **C** denote that point on the moving body that traces a path. Define the following distances:

$$a = |\mathbf{AC}| \quad b = |\mathbf{BC}| \quad c = |\mathbf{AB}| . \quad (1)$$

In class we showed that the *fixed centrode* (the locus of poles, as seen by a fixed observer) was a circle of diameter c . Show that the *moving centrode* (the local of the poles as seen by an observer positioned on the moving bar) is a circle of diameter $c/2$.

Problem 6: (10 points) In class we used the particle nature of rigid bodies to “prove” that a planar rigid body has three degrees of freedom. Use the same idea to spherical motion has

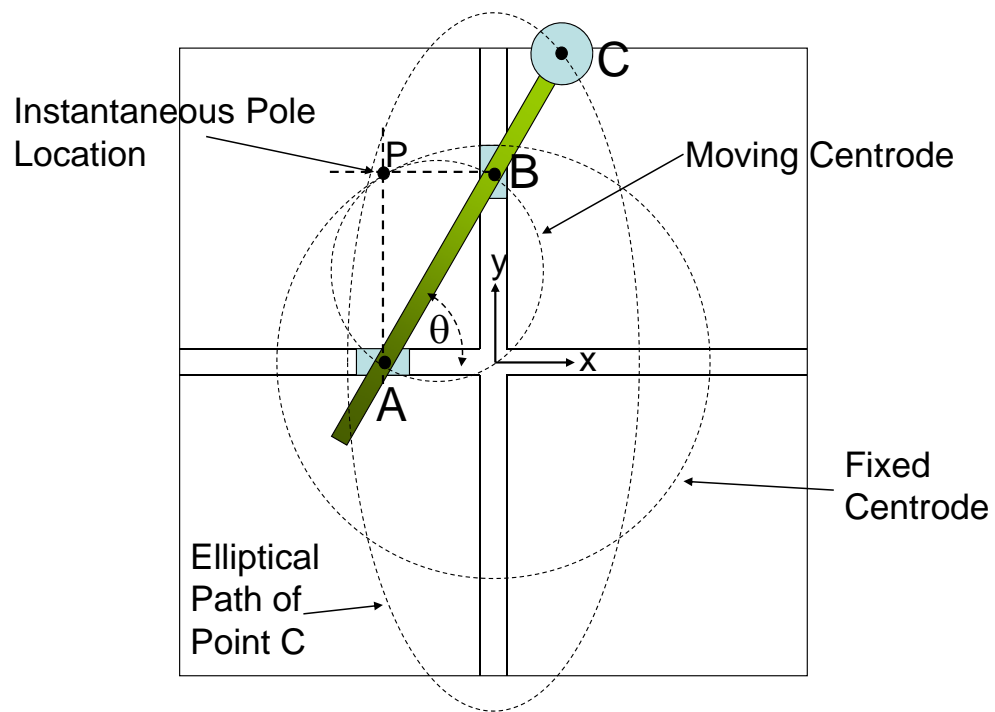


Figure 1: Diagram of the Elliptical Trammel, showing the geometry of the elliptical path, as well as the fixed and moving centrodes (dashed circles).

three degrees of freedom. (Hint: use the definition of a rigid body as a set of particles, and then calculate the total net degrees of freedom of the rigid body based on the particles and their constraints).